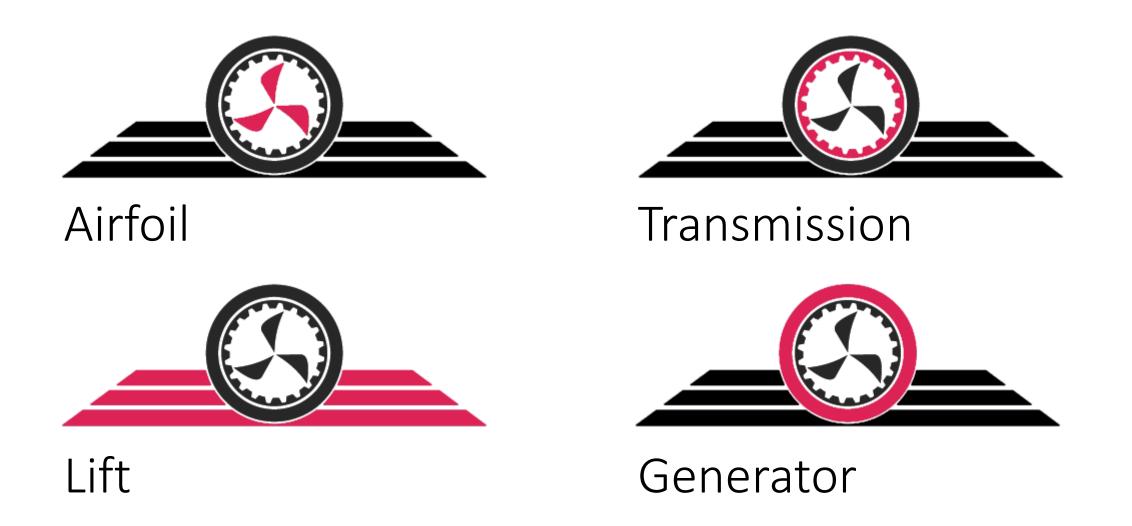
# Practical experiences with a torsion based rigid blade Rotary Airborne Wind Energy System with ground based power generation

**Christof Beaupoil** someAWE Labs S.L.

**AWEC 2019** 

christof.beaupoil@gmail.com

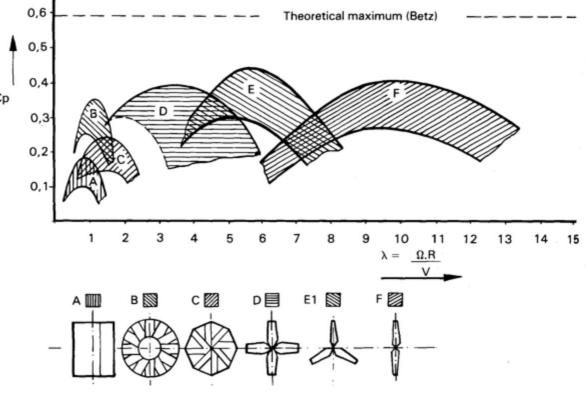
#### When Loyd is just too mainstream for you...



## When Loyd is just too mainstream for you...



#### My Airborne Rotor (MAR1)



FAO IRRIGATION AND DRAINAGE PAPER 43, Water lifting, by P.L. Fraenkel

Goal: as small and slow as possible while still efficient 120rpm | nominal wind speed of 10m/s

$$TSR = 3 = \frac{v_{tip}}{v_{wind}} = \frac{2 * \pi * r_{rotor}m * rps}{10 \frac{m}{s}} \P$$

$$r_{Rotor} = 2.4m \, \P$$

FX 63-137 airfoil from
UIUC Airfoil Coordinates Database
Designed for low Reynolds number applications on small wind turbines by the UIUC Applied
Aerodynamics group as part of their Low-Speed
Airfoil Test program



# My Airborne Rotor (MAR1)

		Wind speed	10	m/s	ср	0.1
HubDiagonal	60	1524		HubStrut	42.4	
BladeStub	22	558.8				
Blade	26.0	660				
Rotor Radius	78.0	1980.8				
	inch	mm				
HubDiagonal	60	1524		Area total	10.99	sqm
BladeStub	20	508		Area stubs	5.07	sqm
Blade	23.6	600		Effective Rotor Area	5.92	sqm
Rotor Radius	73.6	1870				
Inner Blade radius	50.0	1270		Power	364	W
	inch to mm	25.4		$A_{effective} = \pi (r_{tip} -$	$-r_{\epsilon_0(t)})^2$	$= \pi (1.87 - 1)$

 $P = \frac{1}{2}1.23 \frac{kg}{m^3} 5.92 m^2 10^3 \frac{m^3}{s^3} 0.1 = 364 W$ 

# My Airborne Rotor (MAR1)

Part	Description	Quantity	Weight/ Unit (LB)	Weigh/Unit (g)	Weight total (lb)	Weight total (g)
Blade	Foam core with two 0.2" carbon tube spars and Ultracote polyester covering; Foam Type: EPP; Wing Span: 24"; Airfoil: fx63137sm; Chord: 6"	4	0.175	79	0.7	318
Hub		1	0.55	249	0.55	249
Rotor total					1.25	567

#### When Loyd is just too mainstream for you...





# Base/Generator

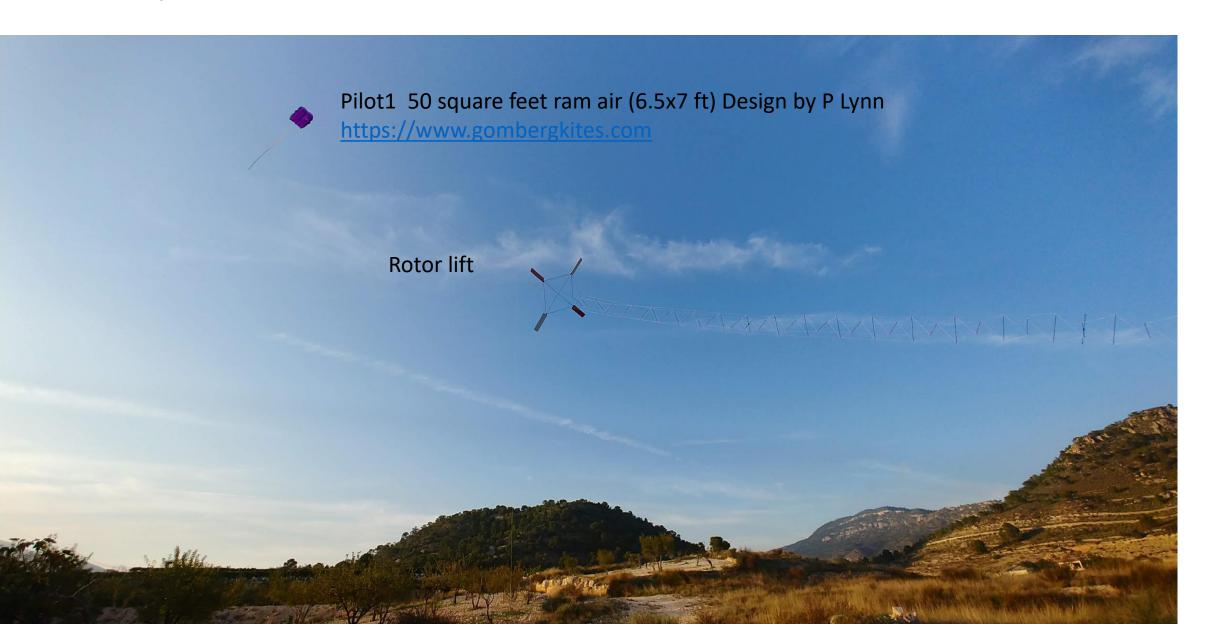
- BLDC 60Kv
- 6:1 Belt drive
- VESC
- Gimbal
- 8 Load cells & amplifiers ESP32
- Power sink (battery, beer cooler, resistors)



## When Loyd is just too mainstream for you...



# Cheap & dumb Lift



# When Loyd is just too mainstream for you...

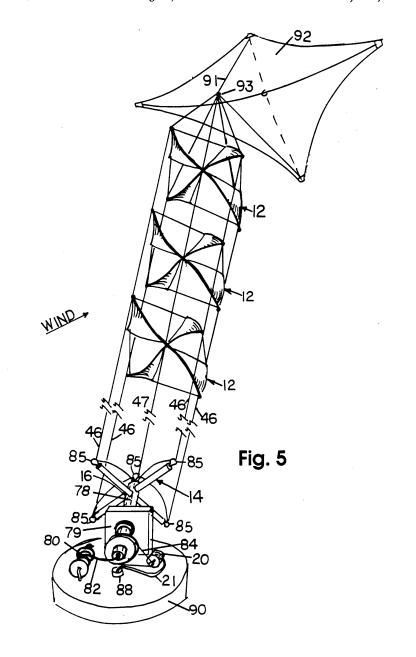


#### Coaxial multi-turbine

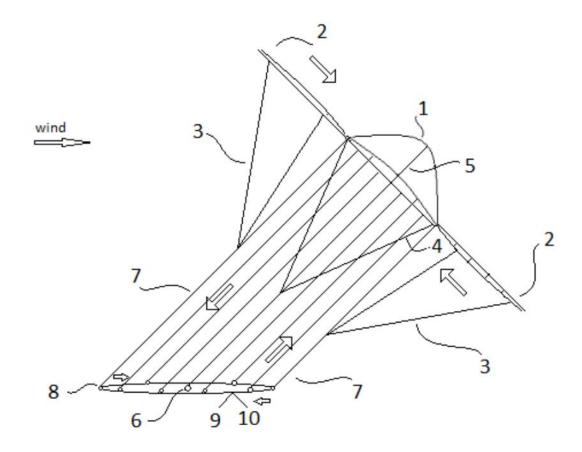
"Driver lines attached to the extremities of the turbines transmit this energy to the extremities of the hub structure"

R. W. Harburg, \Coaxial multi-turbine generator," 20 1991, uS Patent 5,040,948.

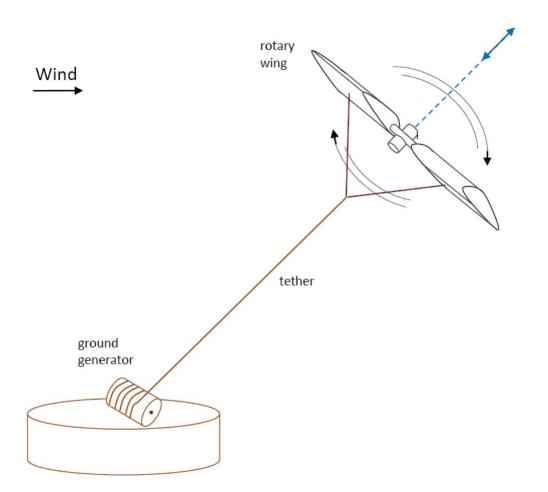
U.S. Patent Aug. 20, 1991 Sheet 5 of 6 5,040,948



## Rotating Reeling

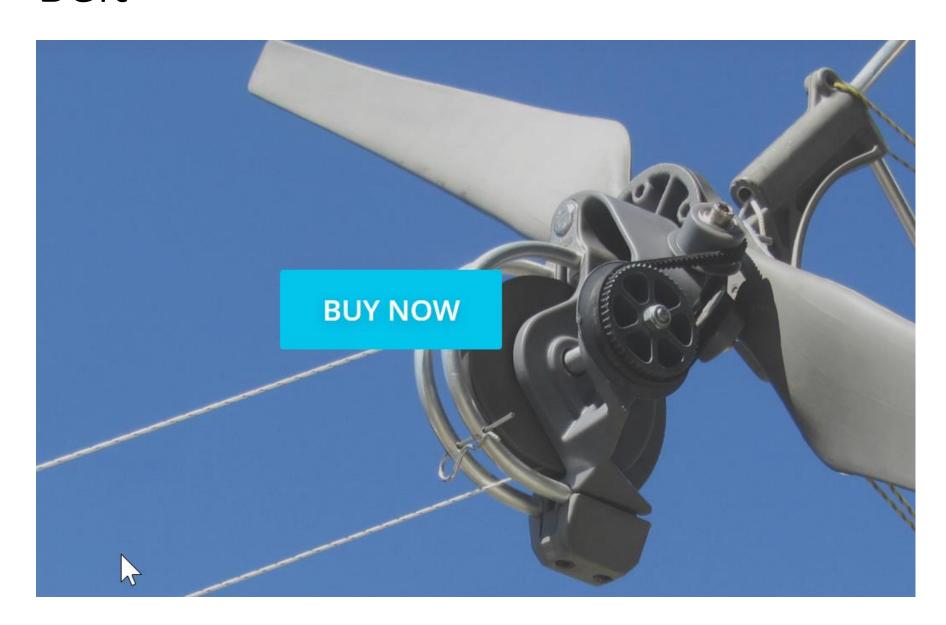


# Reel in/out



Leo Goldstein - Airborne Wind Energy Systems with Rotary Wing and Ground Generator

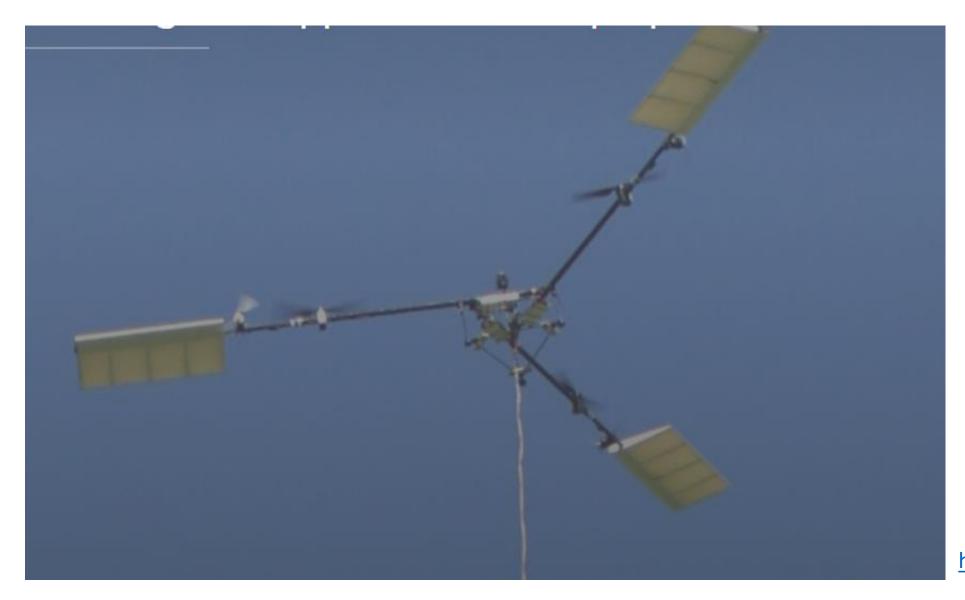
# Belt



# Flygen / Multirotor / Autorotation



# Flygen



http://bladetipsenergy.com

# Torsion / Shaft



# TRPT - Tensile Rotary Power Transmission



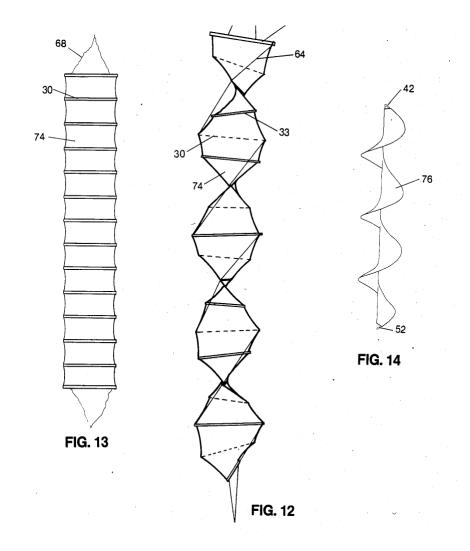
Rod Read <a href="https://windswept-and-interesting.co.uk/">https://windswept-and-interesting.co.uk/</a>

#### Torsion

US4708592A Helicoidal structures, useful as wind turbines

"A collapsible structure comprising a non-rigid helicoidal sheet braced by light-weight members"

"flexible fabric sheet (21) is reinforced by wires (42) sewn into its edges, and may be further reinforced by ribs or battens (30) sewn crosswise into the sheet"



US4708592A Krolick et al. "Helicoidal structures, useful as wind turbines"

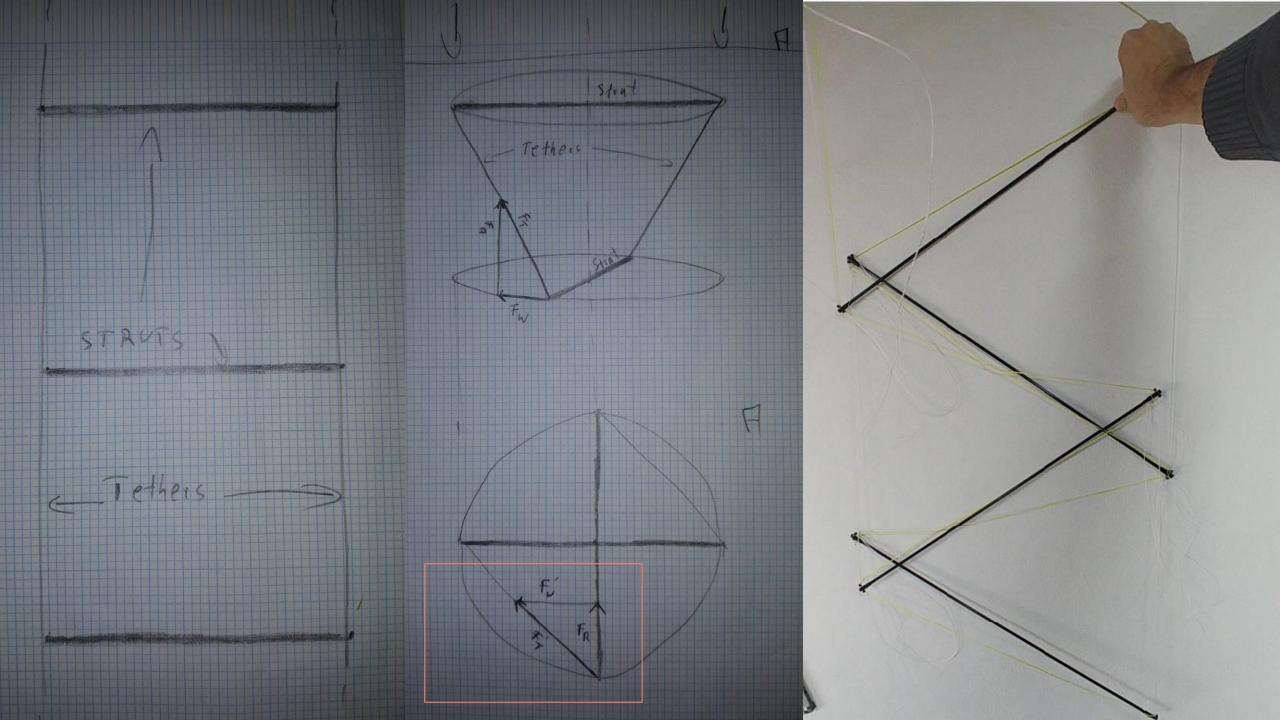
#### Tensegrity

**Tensegrity** [...], is a structural principle based on the use of isolated components in compression inside a net of **continuous** tension, in such a way that the compressed members (usually bars or struts) do not touch each other and the prestressed tensioned members (usually cables or tendons) delineate the system spatially.[1]

The term tensegrity was coined by Buckminster Fuller in the 1960s as a portmanteau ensional integrity". [2]

The Skwish Tom Flemons







# Open Tensegrity Shaft (OTS) "Helix"

#### Tensegrity [...]

**Open Tensegrity** is a structure that fulfills the definition of Tensegrity except for the "continuous tension" part. An Open Tensegrity structure allows for an external force to be applied to delineate the system spatially. In AWE this force would likely be a lift force generated by an airfoil.

**Shaft/Driveshaft** is "a long cylindrical rotating rod for the transmission of motive power in a machine" [3].

We remove the "cylindrical" requirement. We define any rotating three-dimensional long structure for the transmission of power a "Shaft".

**Open Tensegrity Shaft / OTS** Combining the definitions of "Open Tensegrity" and "Shaft" an OTS is defined as a:

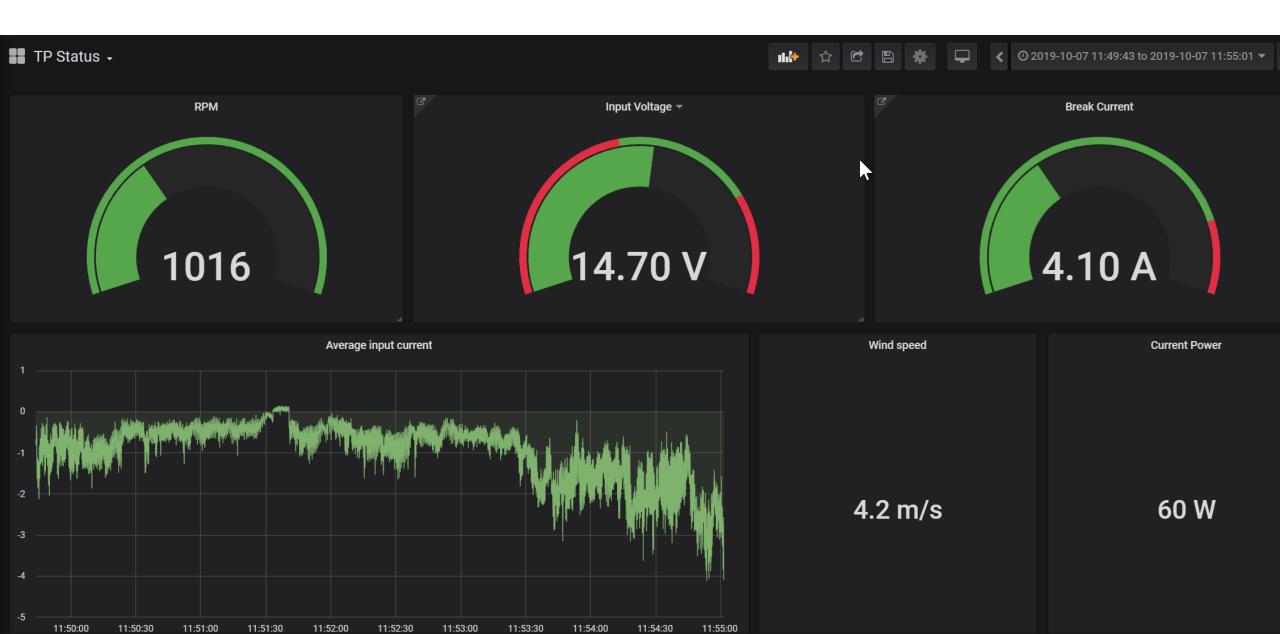
Rotating three-dimensional long structure made of components in compression (struts) and tension (tethers) for the torsion based transmission of power.

#### Our Helix

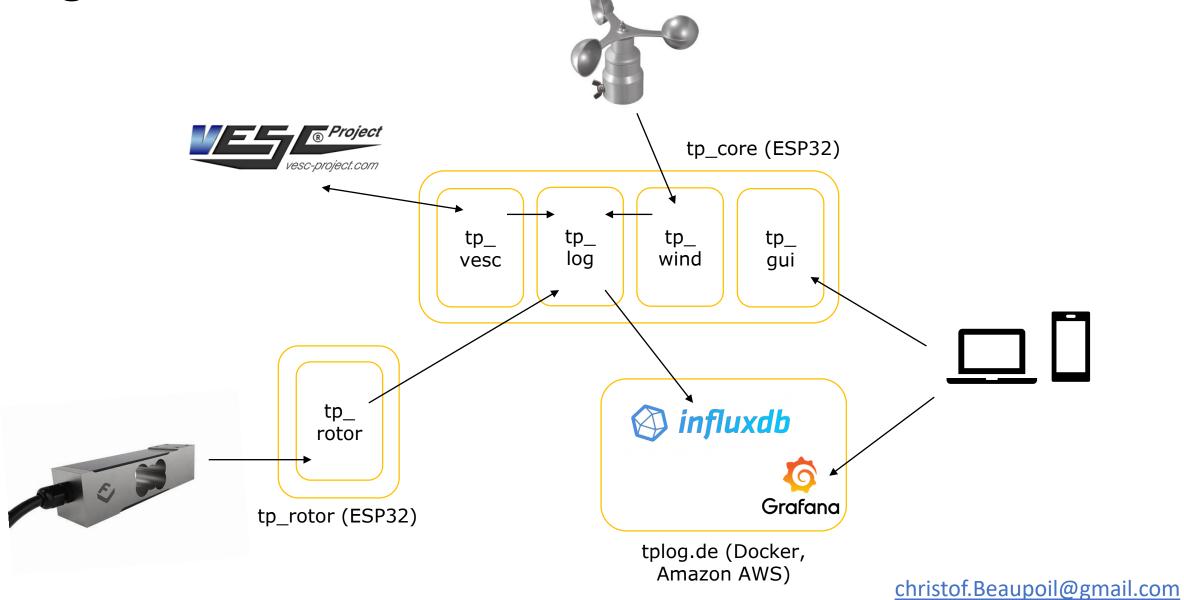
- 5\*500mm: smallest wound CFK tubes available
- Spacing between rods: Tetrahedron =1/sqrt(2) ~70% ("because it feels right")
- Length 30m because Tüddeln is hard

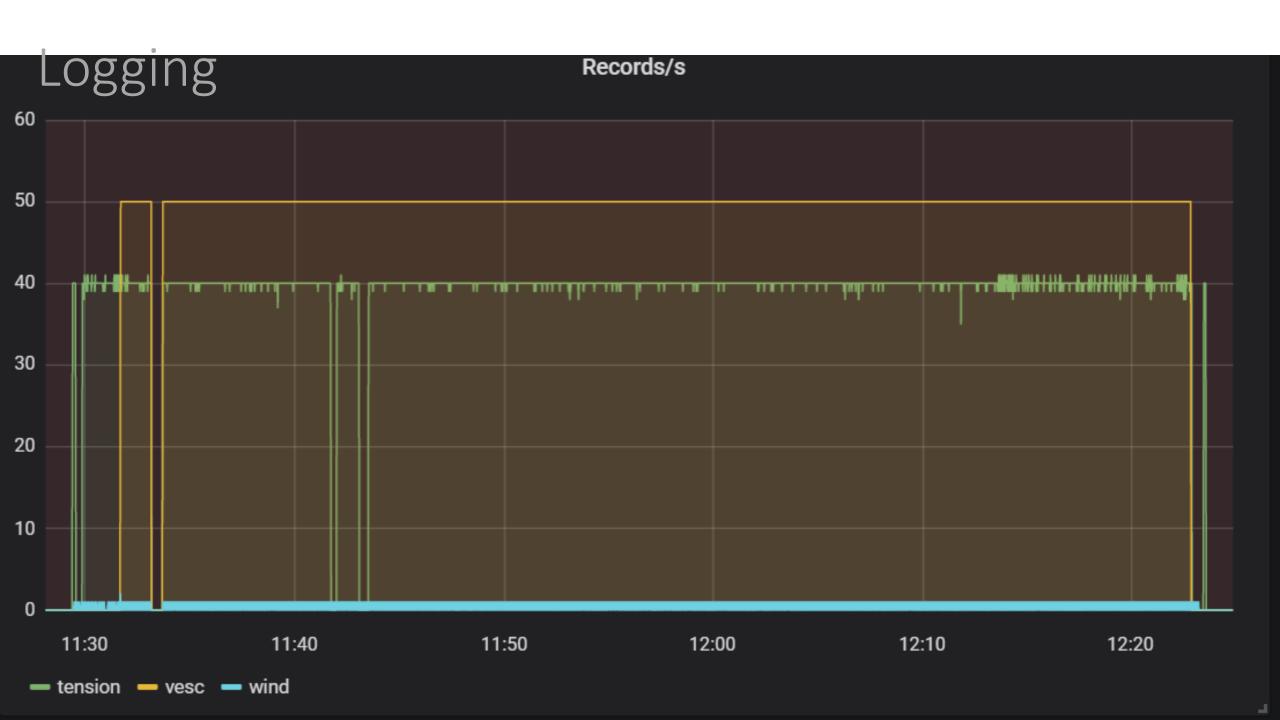


#### DATA

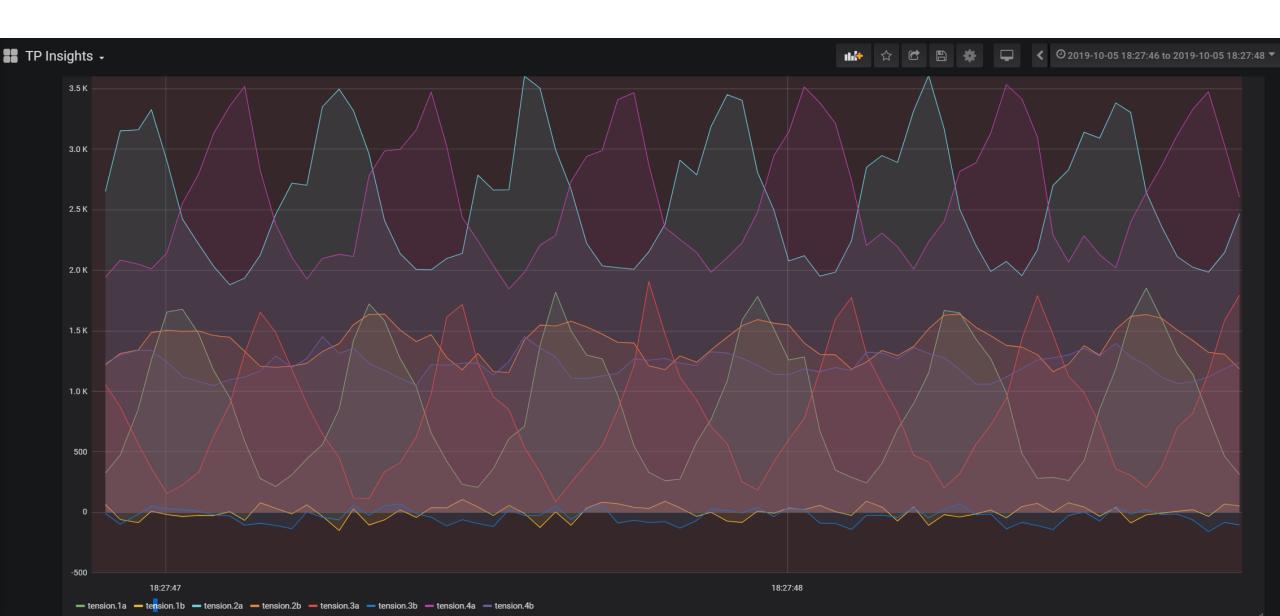


#### TPLog: Overview

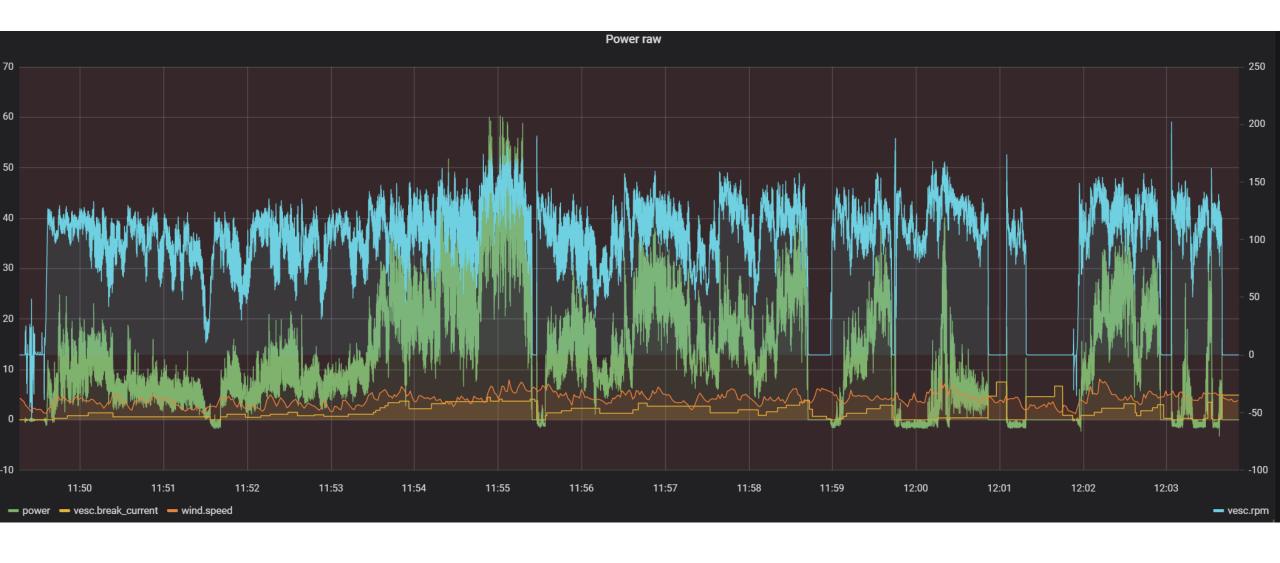




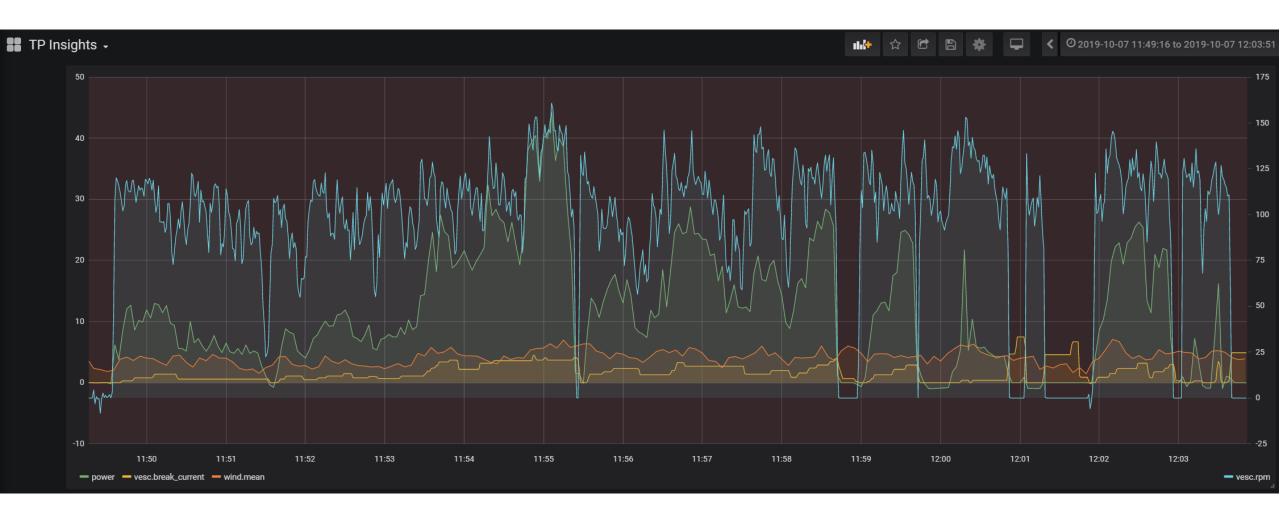
# The Wobble (on testbench)



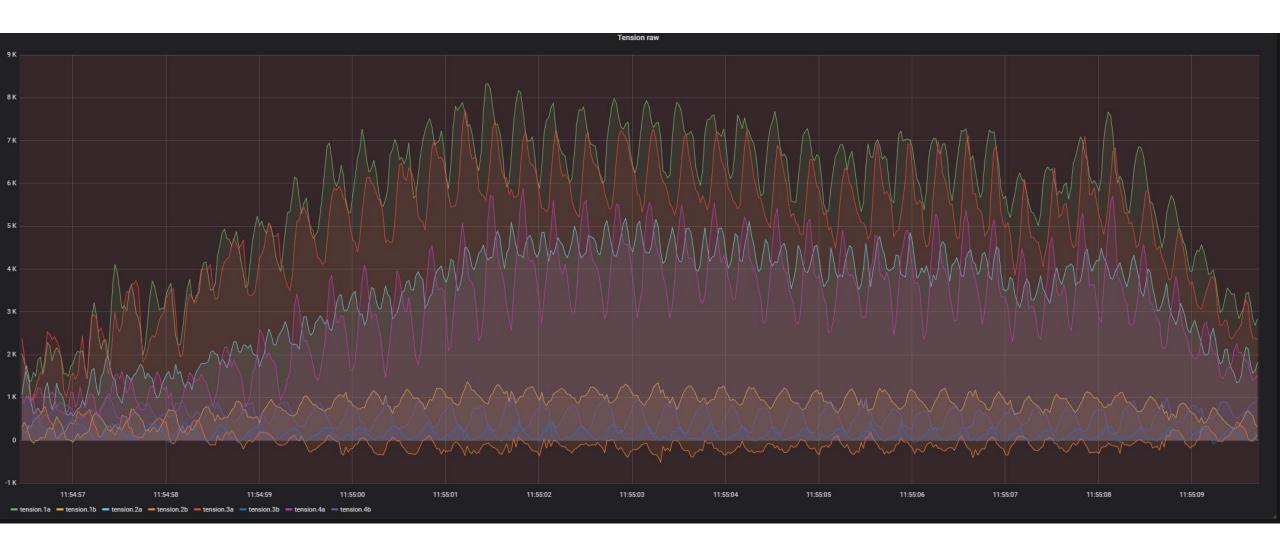
#### Power over wind – raw data



#### Power over wind



# Forces @ peak power



# Technology Road Map

- Measure OTS efficiency&optimise f(length, RPM, torque, diameter)
- Understand OTS dynamic behavior (wobble & skipping)
- Build & document 500W @ 100ft
- Add launch and retrieval capabilities

Anybody wants to build a model of the OTS?

# someAWE's secret masterplan

Open Source Business model Linux / Red Hat or RepRap / Prusa i3

Build something useful that works -> have people copy and improve it

The machine is & will be 100% open source

The machine that builds the machine is not

someAWE S.L. will start by distributing components

